**Starting the GrxUI Environment**

Run the following script to enable the control of the simulation:

1. Open the GrxUI: >> cd $(OPENHRPHOME)/bin/unix/
2. Execute GrxUI.sh: >> ./GrxUI.sh
3. If using OpenHRP3.1 or higher: >>   
   cd $(OPENHRPHOME)/Controller/IOserver/robot/HRP3STEP2/bin
4. And executed the following: >> sh OpenHRPController.sh

Load the HIRO Simulation:

1. Change to the following directory: $(OPENHRPHOME)/client/gui/project or $(OPENHRPHOME)/Controller/IOserver/robot/HRP2STEP1/project/
2. Load the appropriate XML file. Possible names are related to HIRP and PivotApproach. i.e. HRP3STEP2-aist.xml
3. Click on the icon with a running man to load the python script.
4. Click on the play button to start the simulation.